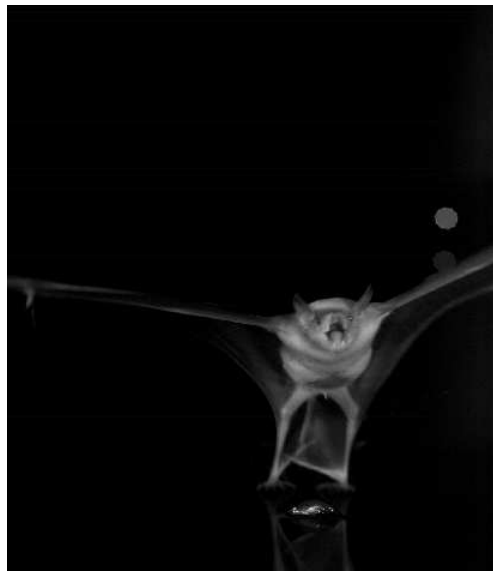


# Applying 3D sensing to novel problems

Bob Fisher

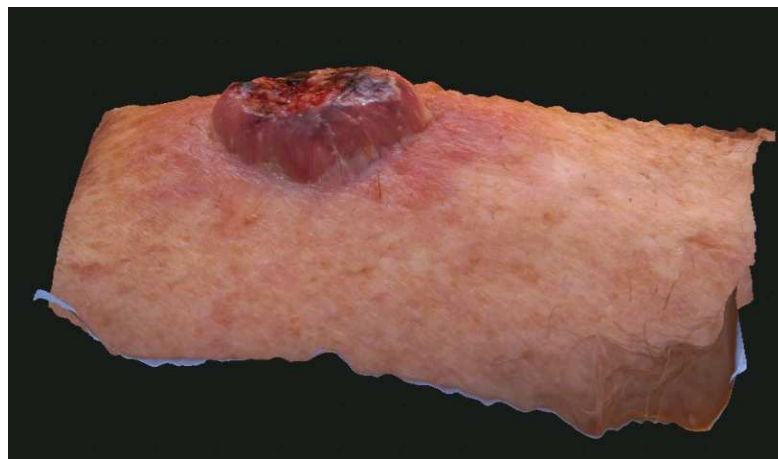
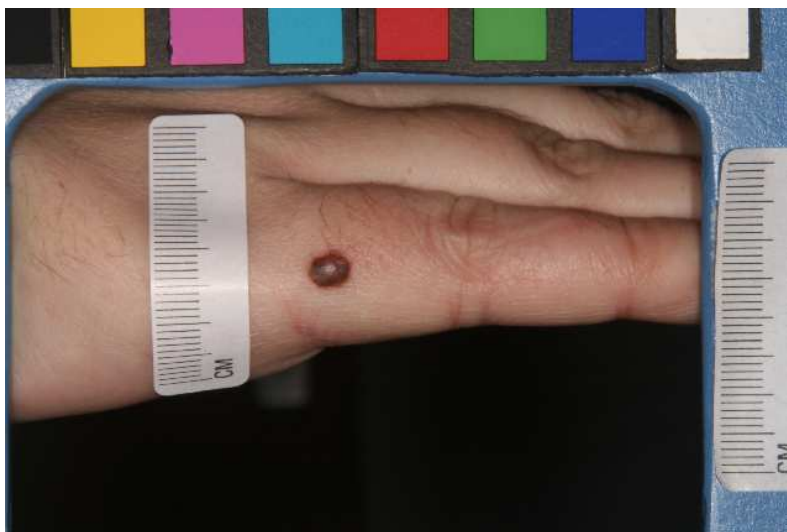
UNIVERSITY OF EDINBURGH



3D skin cancer analysis

Dynamic 3D shape analysis

## Skin Cancer Analysis



Benefit of 3D data for segmentation and classification?

Xiang Li, Lucia Ballerini, Steven McDonagh

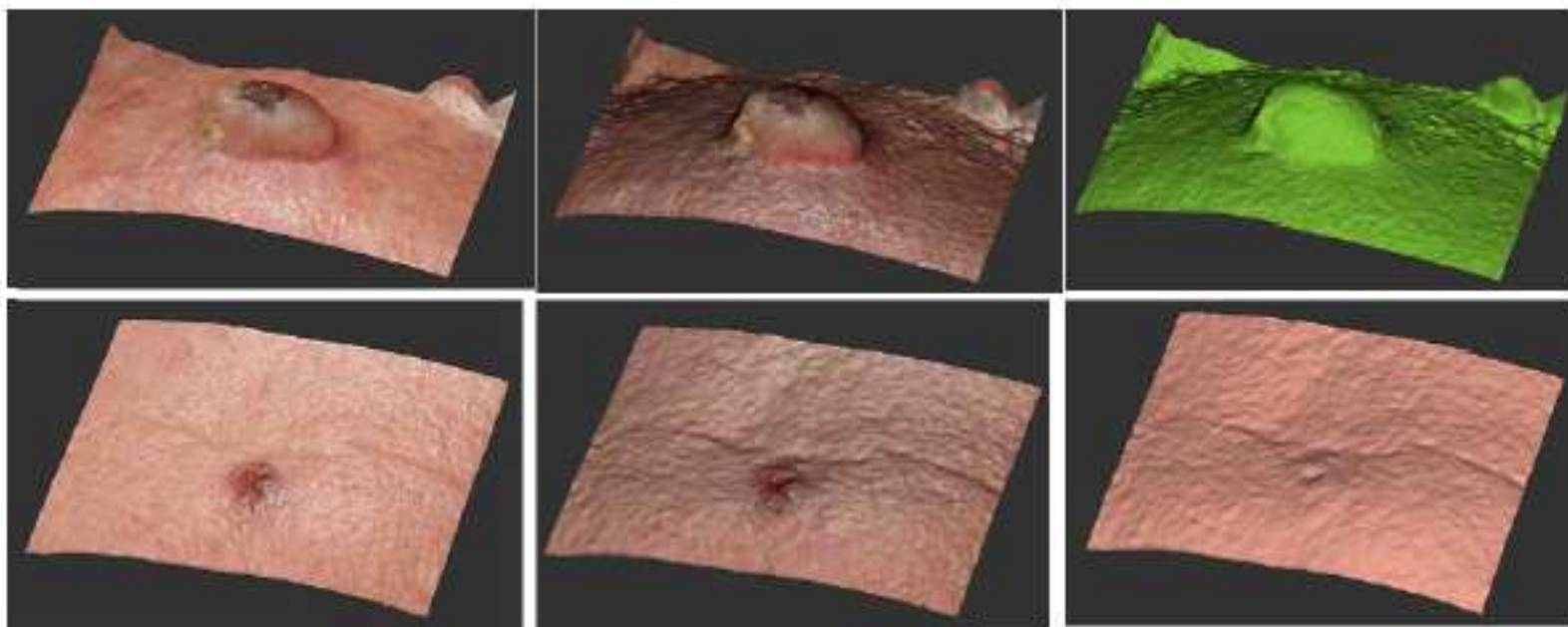
## Stereo Camera System



7 megapixel RGB color digital SLR camera

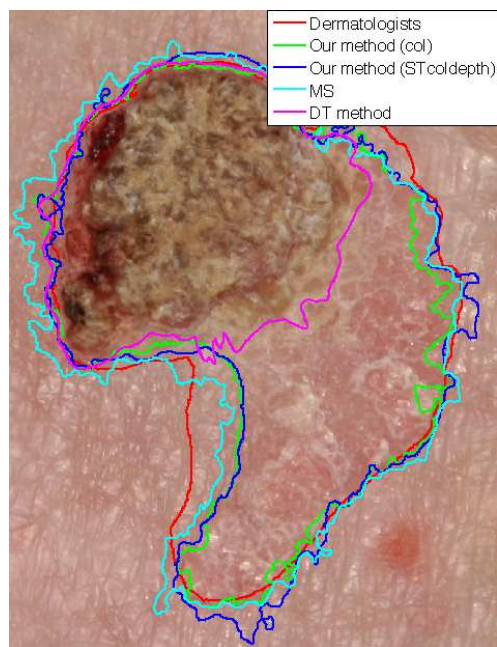
## Typical 3D + Color Data

Registered XYZ data, RMS and sampling: 0.03 mm



# Lesion Segmentation

Using a probabilistic level-set framework



Needed for most diagnosis systems:

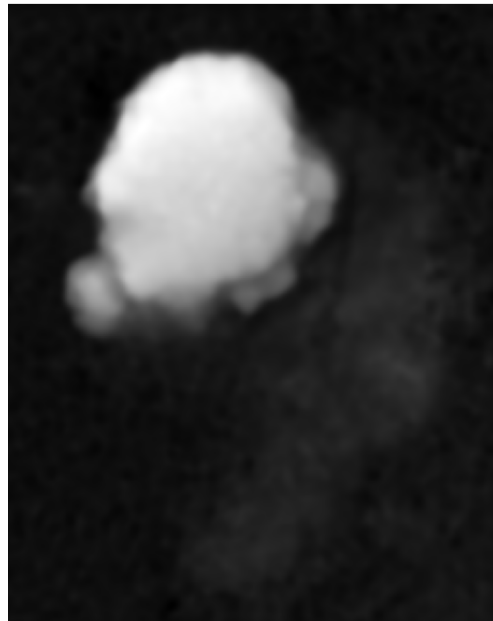
- compare properties inside vs outside
- shape of lesion, eg boundary irregularity

# Lesion Segmentation

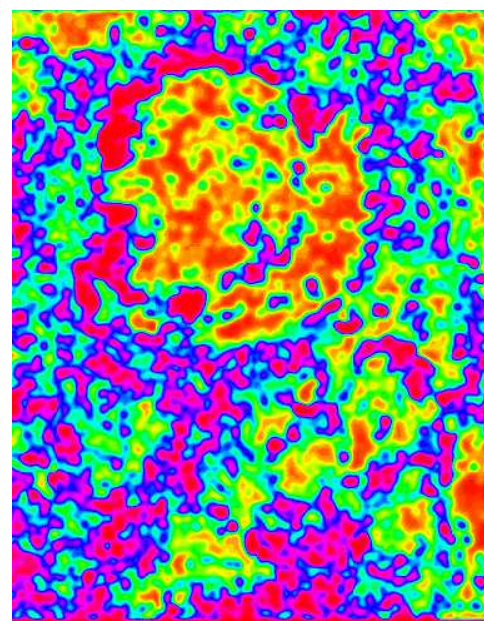
Using 3D and other properties



$a^*$  from  $La^*b^*$



depth

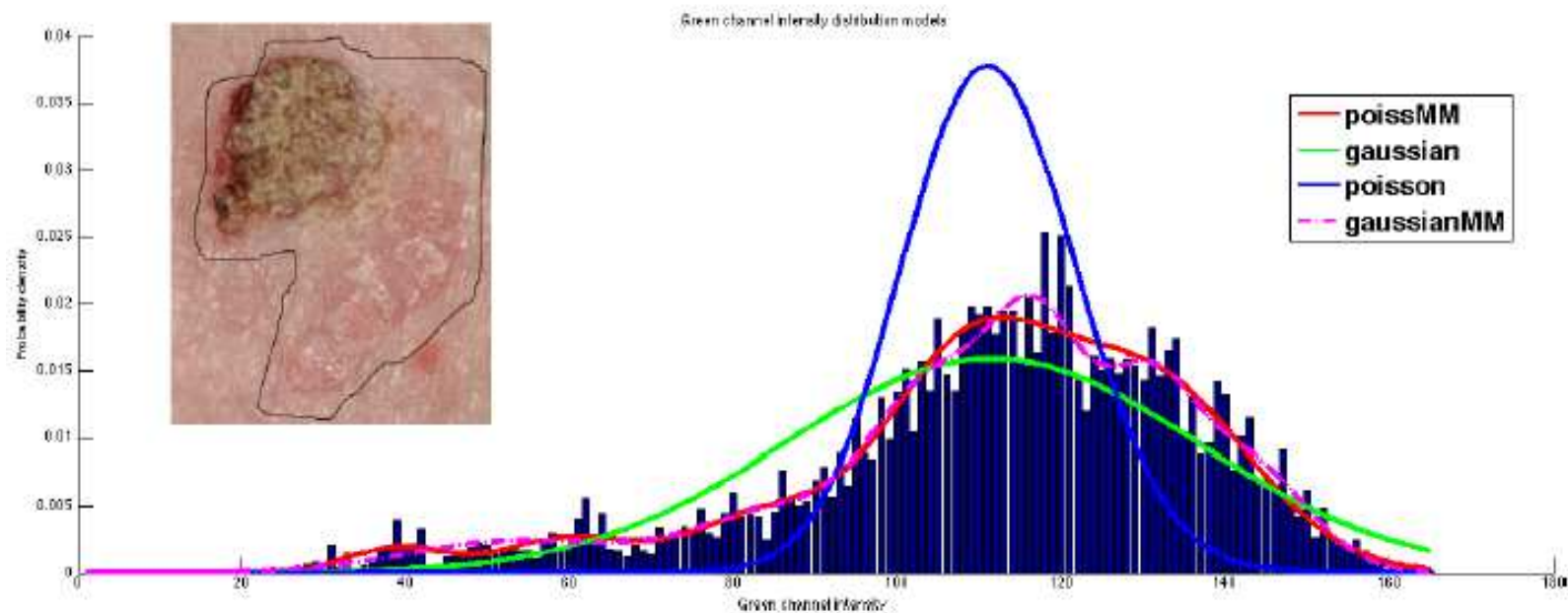


structure tensor

8 properties in total

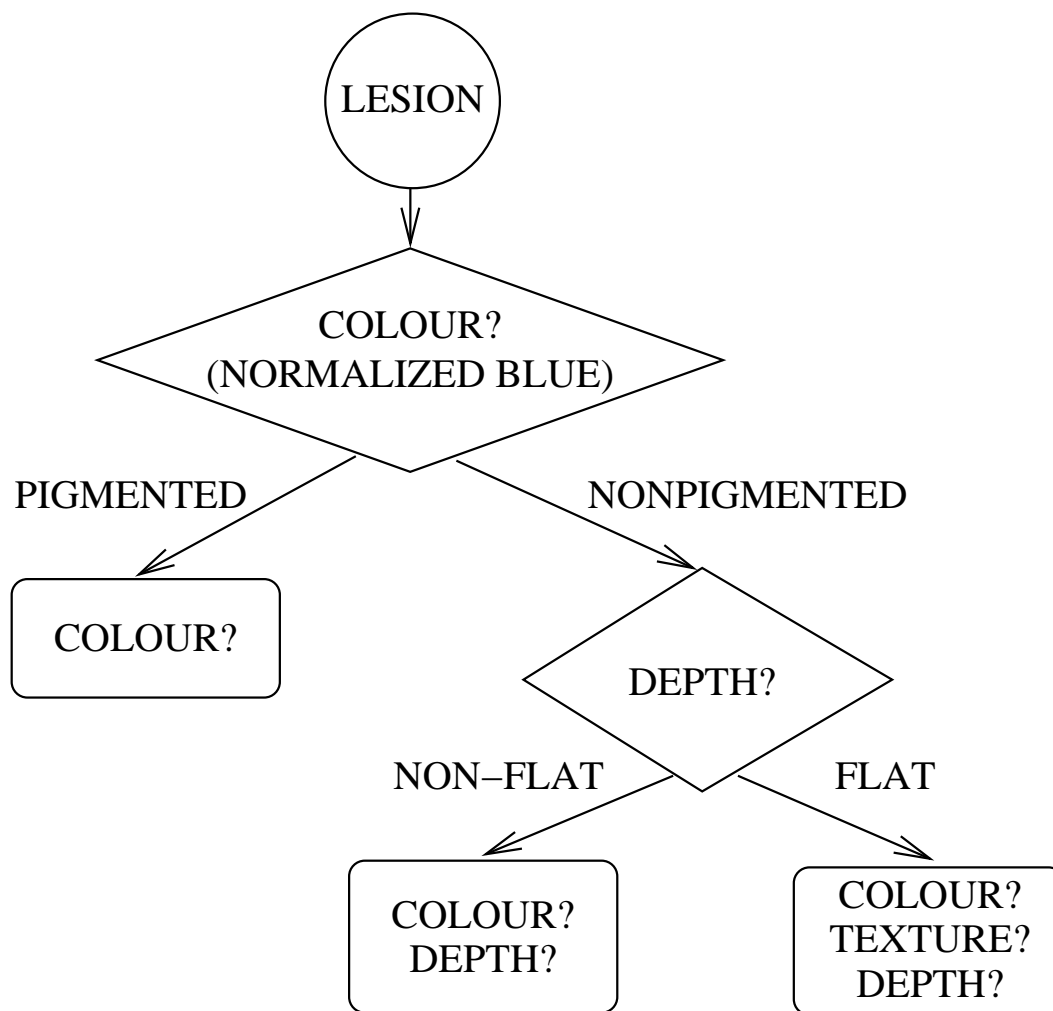
## Skin class models

Used Gaussian Mixture Model to model interior/exterior  
1D example:



GMM: pink, PMM: red, G: green, P: blue

# Two Level Hierarchical Algorithm





## Experiments

20 lesions, 5 classes

8 medics hand-segment

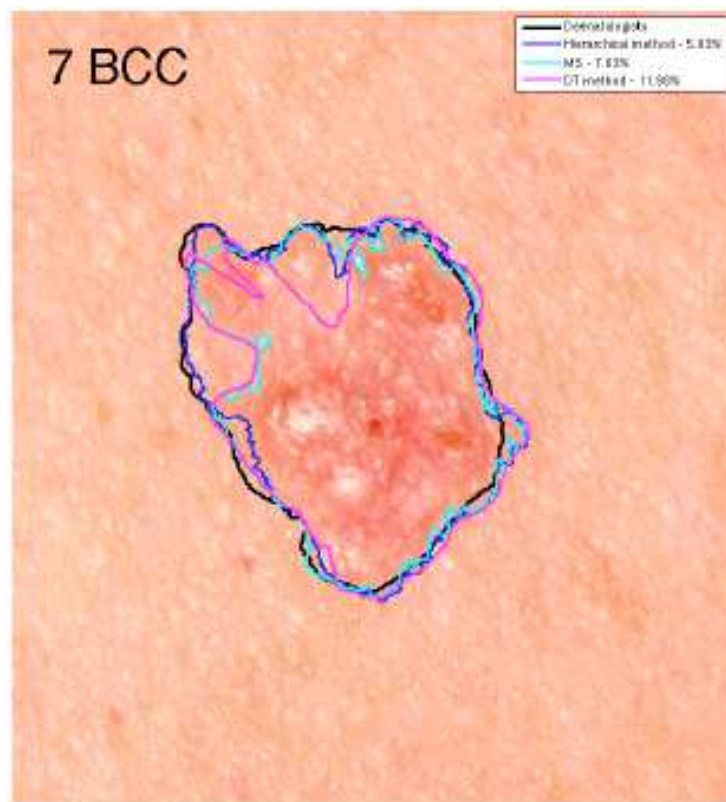
Ground truth: pixels selected by  $\geq 4$  medics

Compared to popular Mumford-Shah automatic region segmentation and Xu's algorithm

XOR evaluation:

$$\frac{\text{algorithm XOR manual}}{\text{algorithm UNION manual}} \times 100$$

## Segmentation Example



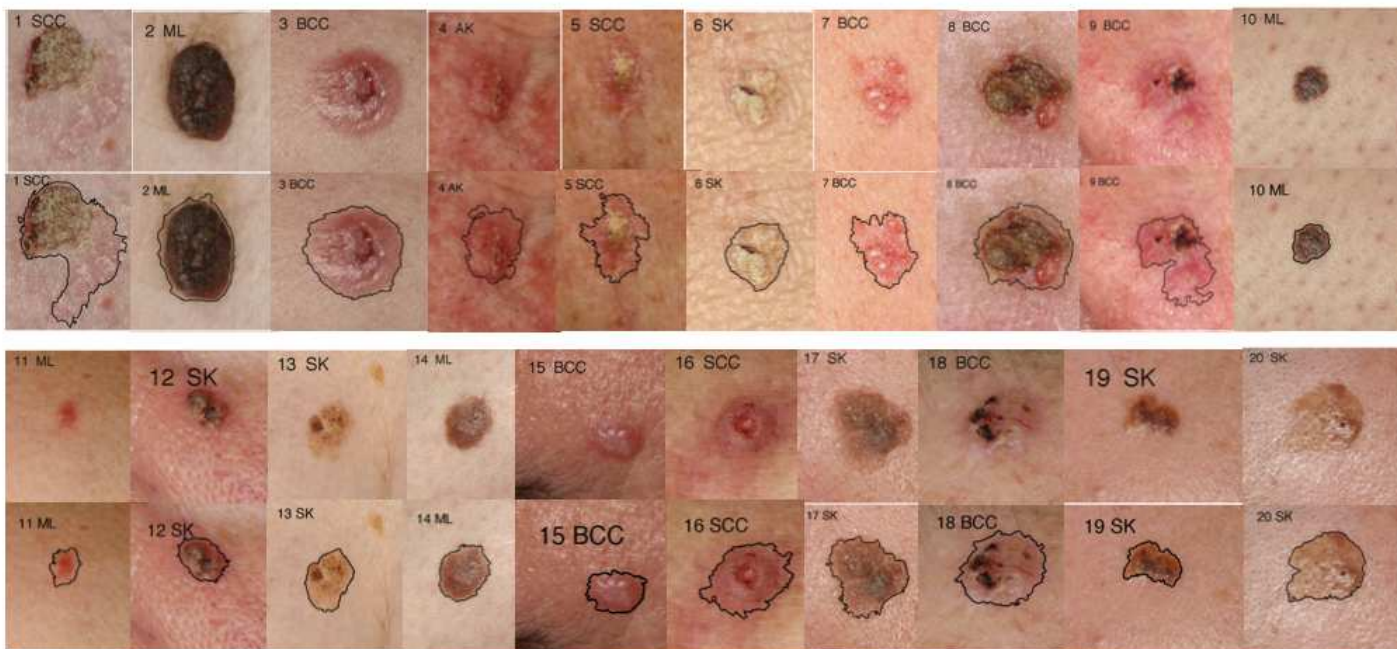
black: manual

blue: new hierarchical

cyan: Mumford-Shah

pink: other

# Twenty Segmentations



## Algorithm Comparison

XOR scores (small is better)

XOR rate	Medics	Flat	2-Hier	MS
All lesions	11.4	9.1	8.7	15.4
Pigmented	6.4	6.6	5.2	10.5
Non-pigmented	14.1	10.5	10.6	18.1

## Skin Cancer Classification Using Depth

Five non-melanoma classes

**AK** - Actinic Keratosis

**BCC** - Basal Cell Carc.

**ML** - Mole

**SCC** - Squamous Cell Carc.

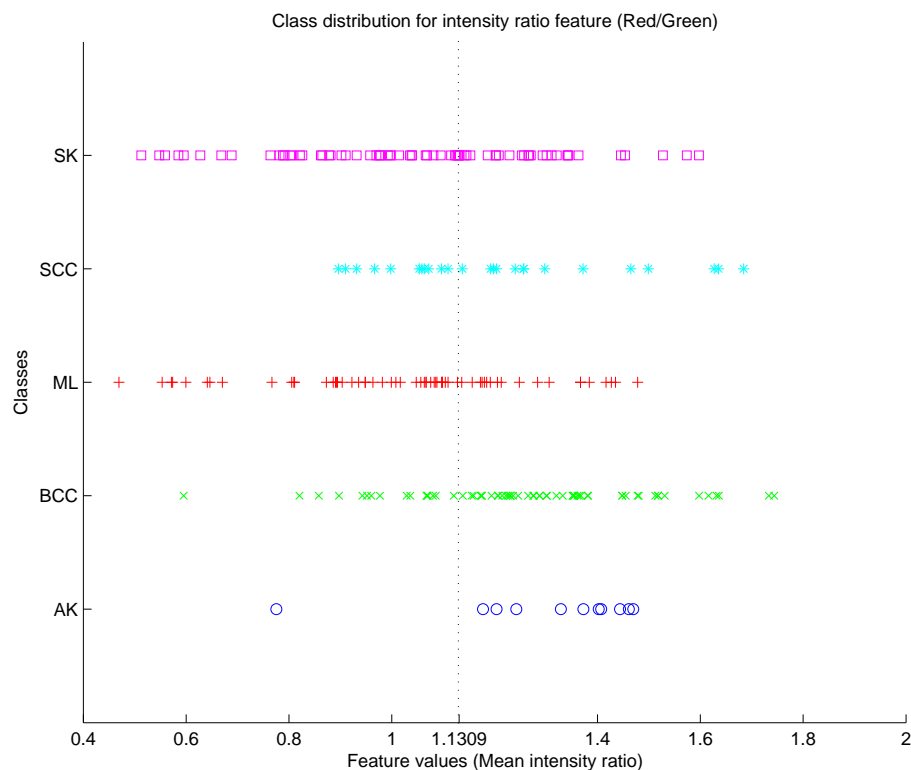
**SK** - Seborrhoeic Keratosis

Most previous research on melanoma only

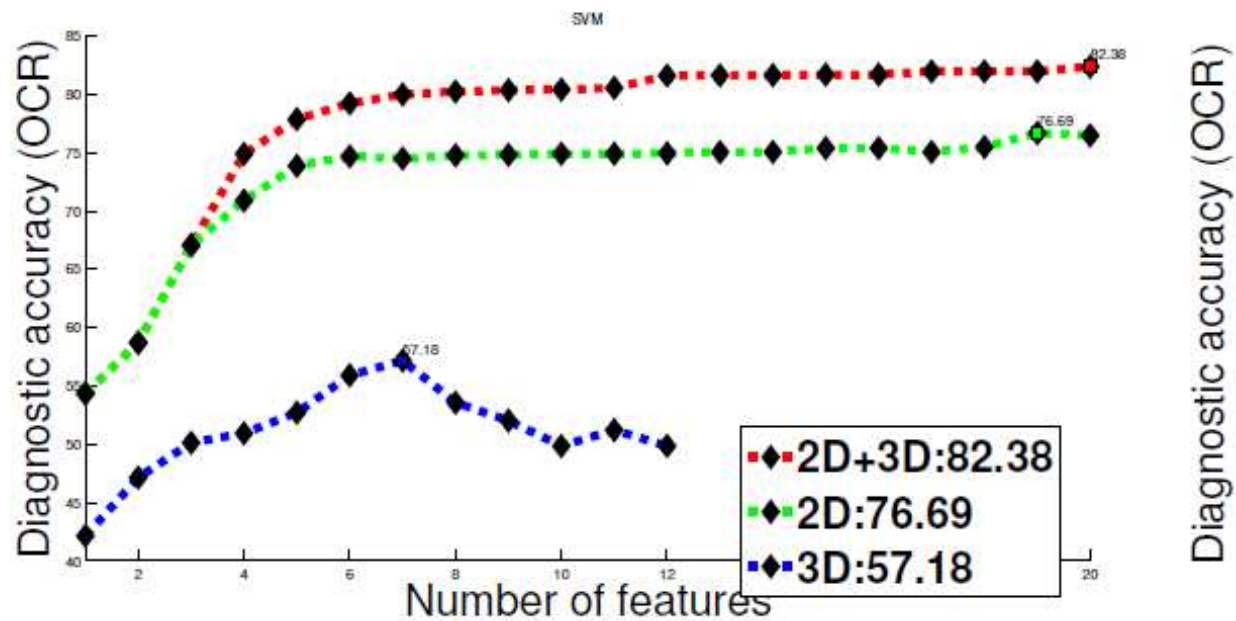
# Skin Cancer Classification Adding Depth

About 50 properties including color, texture, depth

Feature 5:  $(\text{mean green in lesion}) / (\text{mean red in normal})$



# Experiments (smaller dataset)



	Spec	Sens	Acc (OCR)
Color + texture	0.93	0.62	77%
Color + texture + depth	0.95	0.69	82%

(Significant at  $p=0.0002$  for adding depth)

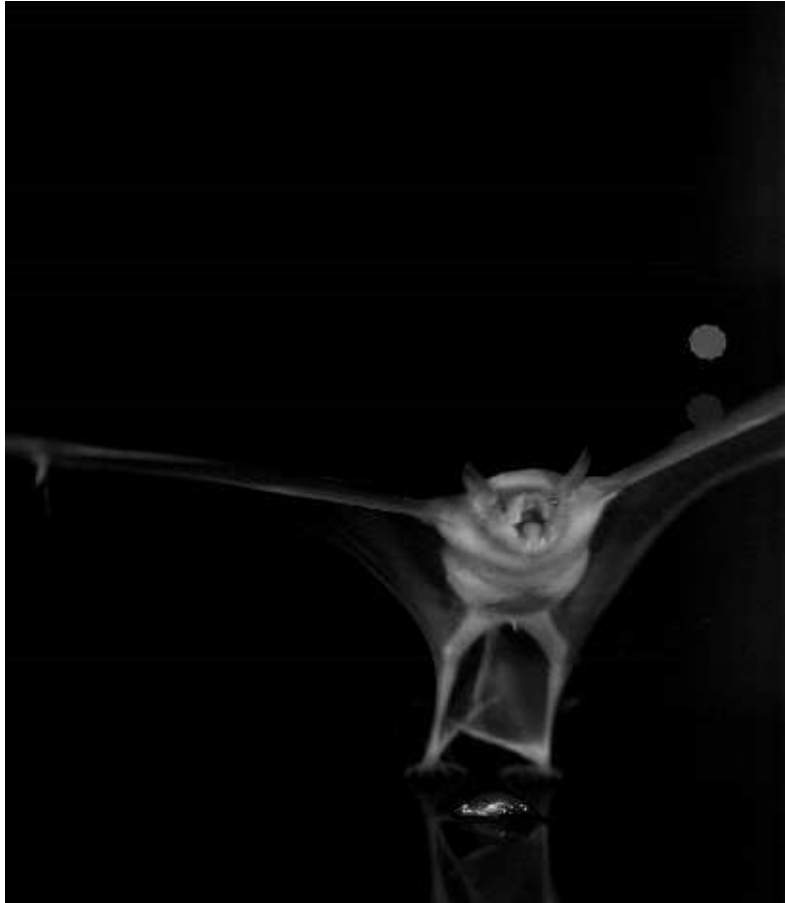
First study on non-melanoma diagnosis (which is  $> 90\%$  on melanoma after 25 years research *versus*  $82\%$  here after 3)



## Application 1 Summary

- Depth data improves lesion segmentation and classification, but may not be economic
- Long way to go to melanoma *versus* mole's 90+% accuracy using specialized devices & 25 years research

# High speed 3D video of bats



Yijun Xiao

## High Speed Stereo 3D Capture

Dimensional Imaging stereo camera system

Unique custom designed sensor

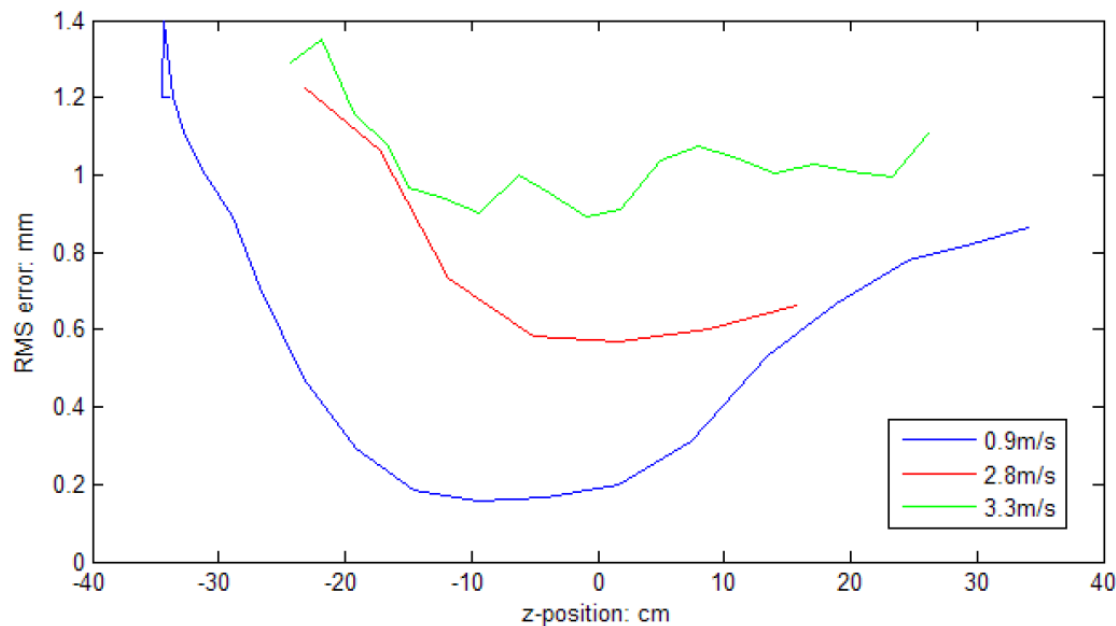


500 Frames per second, 1.3 Mpix/frame, 2 seconds

Infrared sensitive cameras + infrared light panels

Post-capture 3D dense stereo calculation

## Moving Target Performance



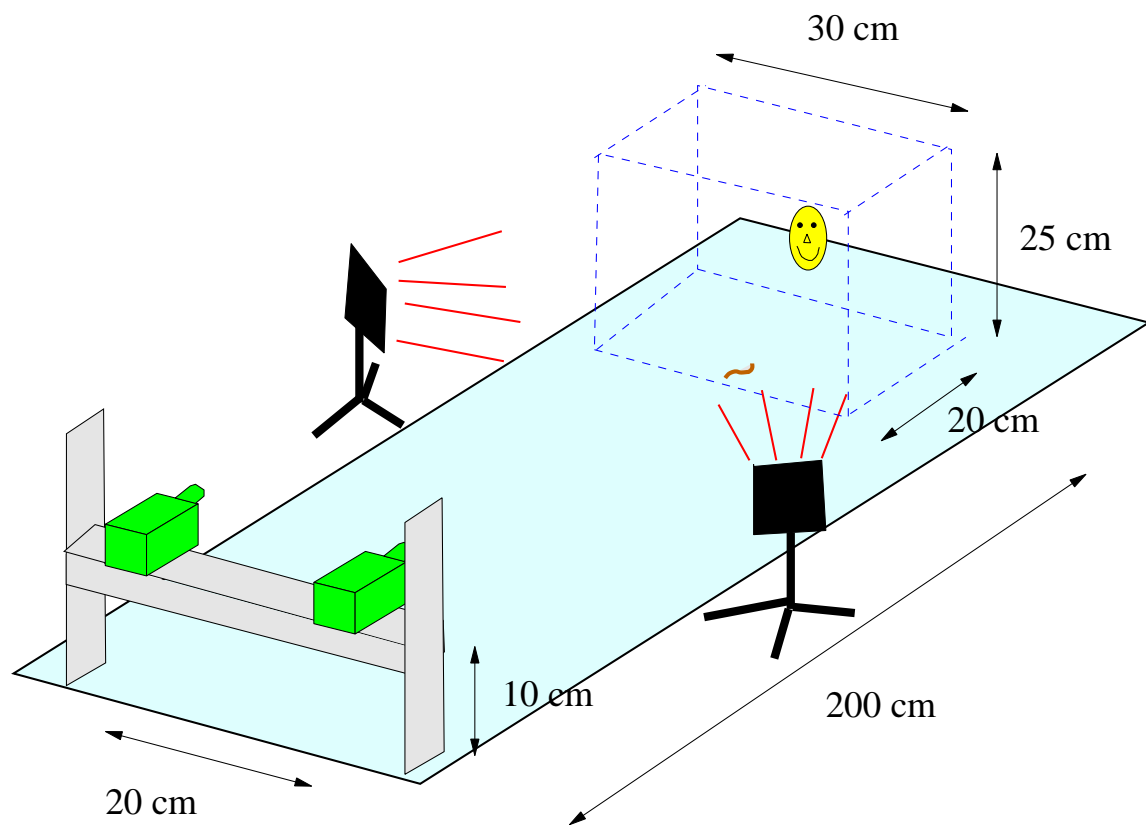
RMS 0.2 - 1.0 mm for looming speeds up to 3.3 m/s

RMS 0.75 mm for vertical speeds up to 5 m/s

RMS 1.4 mm for horizontal speeds up to 2.8 m/s

RMS 0.15 mm over 20 cm depth of field for static targets

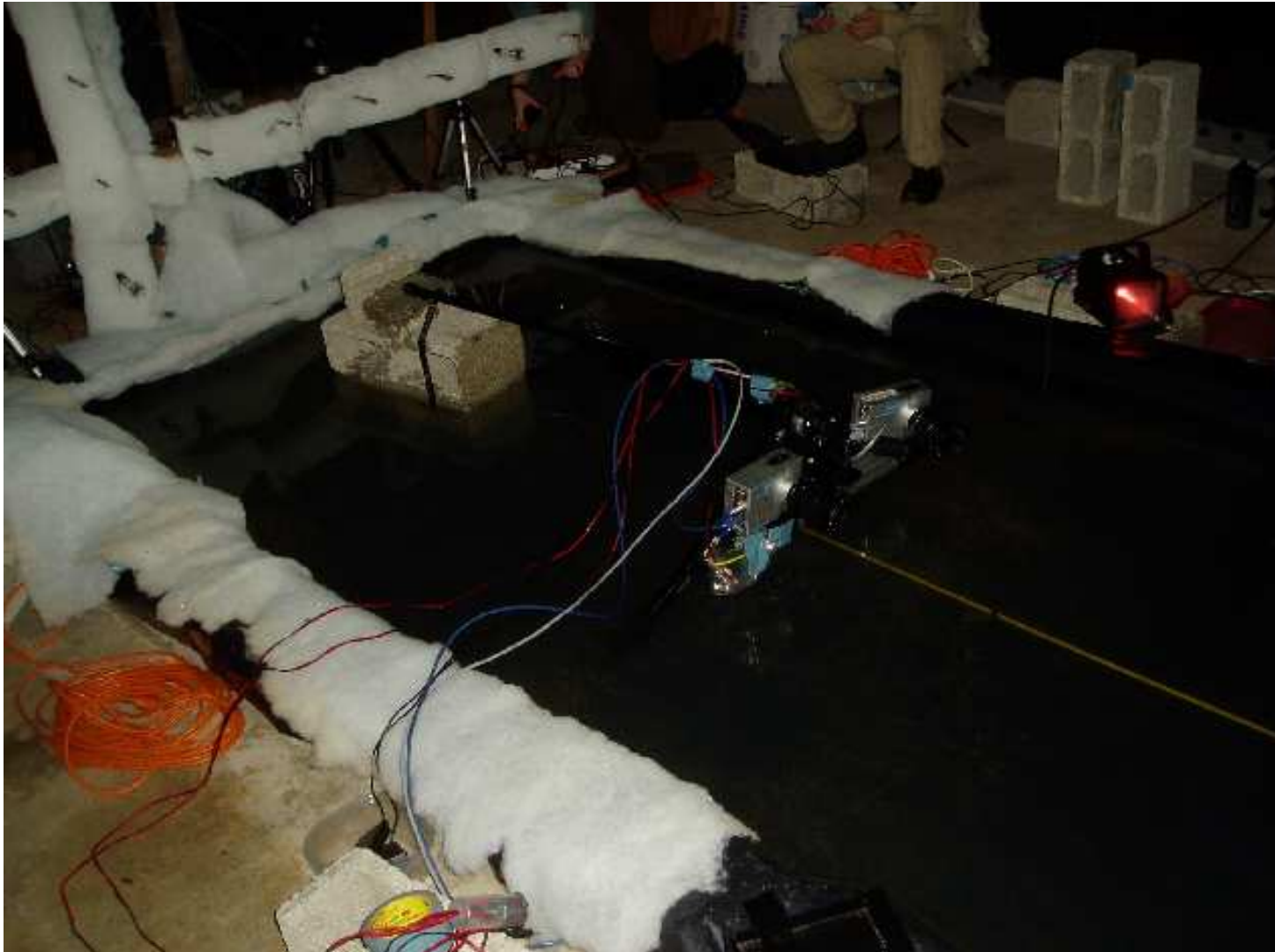
# Trawling data capture scheme



# Bat data capture I



## Bat data capture II



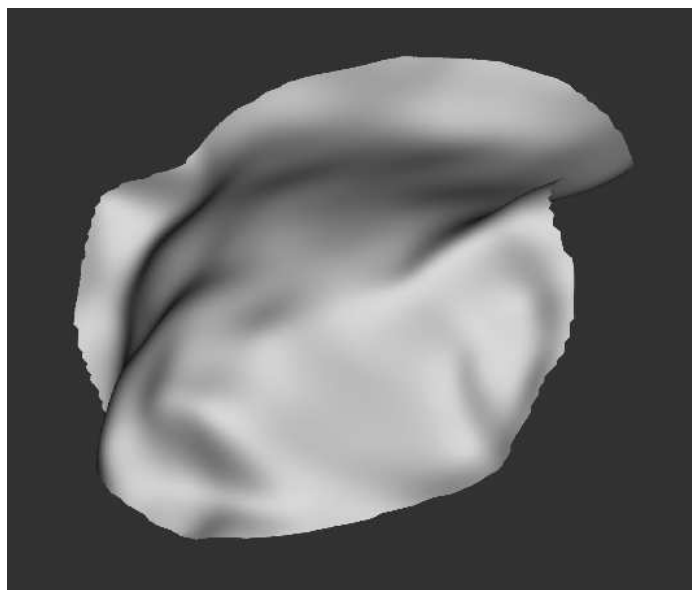
## Stereo Bat Video

2009\_03\_21\_Session5

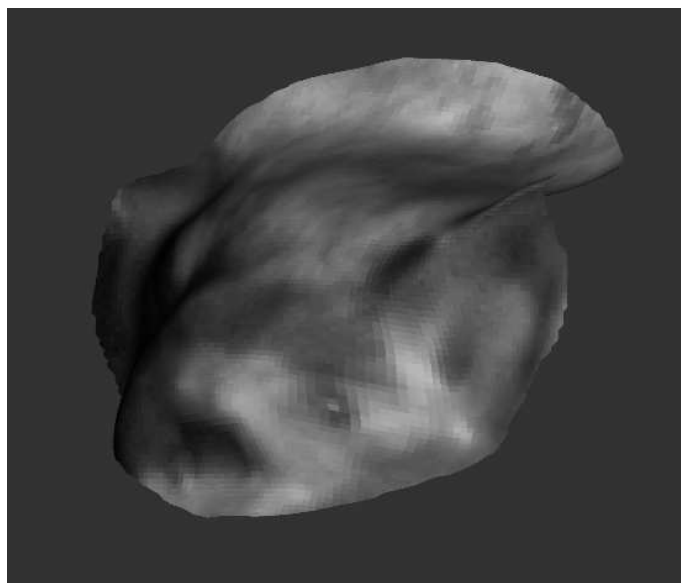
3D bat: 3D\_flying\_bat



# Bat data 3D surface capture



Cosine shaded 3D

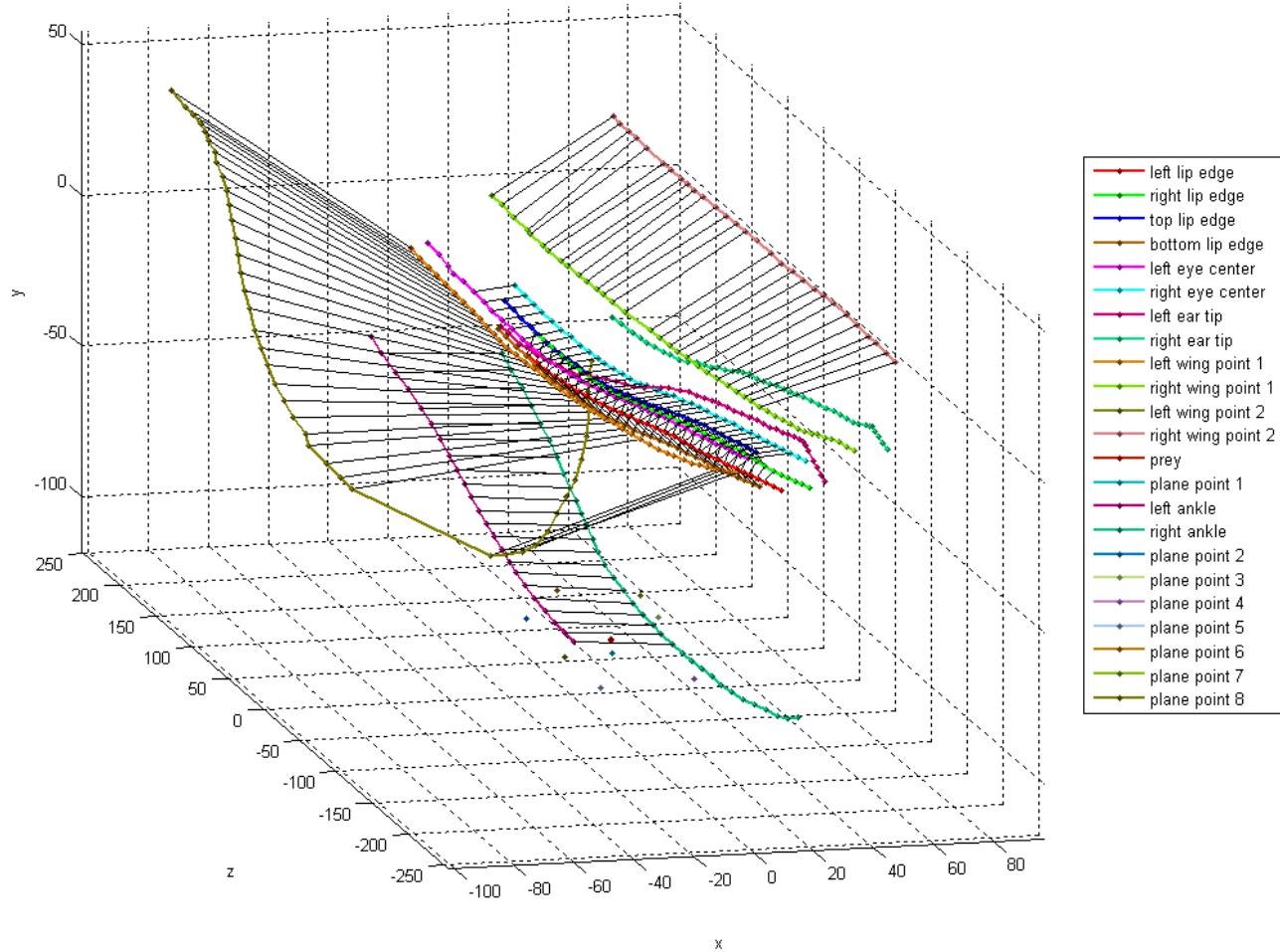


Texture mapped

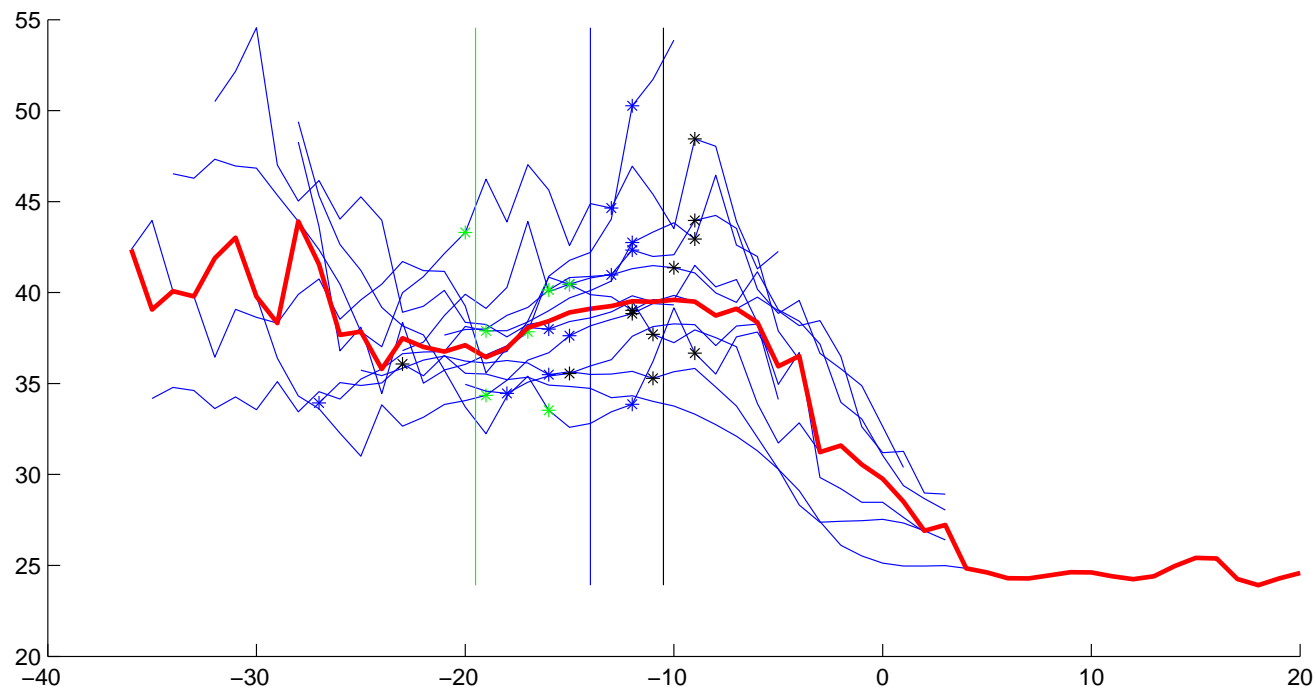


# 3D Tracked Points over Time

Landmarks - Panama 2009-03-20 Session14



## *N. leporinus* Ear Tip Separation



Lola, 13 runs (blue), median (red), prey contact at 0  
Observation: ears elevate as bat starts new search calls

## Application 2 Discussion

1. Goal: link 3D data of bat's behaviour during target acquisition: head, ear and nose leaf orientation, mouth opening, head shape to acoustic behaviour
2. ChiRoPing EC project: build better robot acoustic sensor
3. 500 FPS sensor + software gives useful 3D data, but needs more extension to get more surface detail + smooth temporal data

## Conclusion

1. Novel 3D sensing enables new ways to look at problems
2. Explosion of 'Kinect' applications
3. Expect many more: surveillance, monitoring, performance assessment, ...